

by Schneider Electric

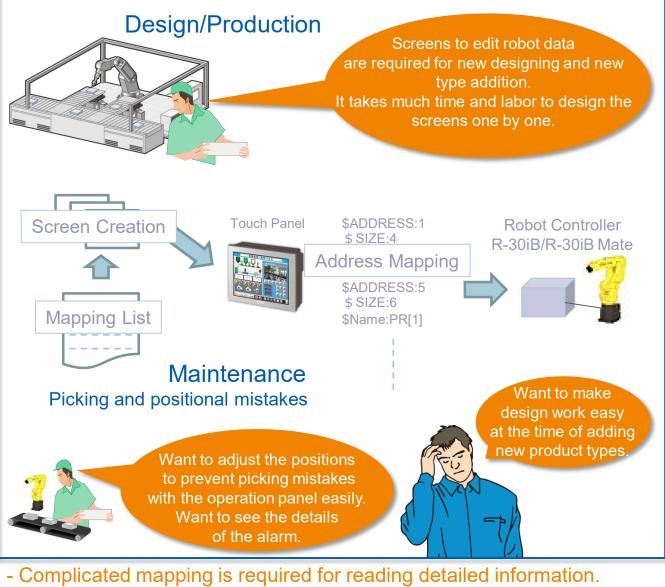


## FANUC ROBOT (R-30iB/R-30iB Mate) MODBUS SAMPLE PROJECT

- Simplified address mapping on the panel!
- Creating screens for position adjustment only by setting!

## Problem (Before) - Robot system designers - Production/Maintenance engineers

Robot data adjustment screens: Needs designing man-hours. Position adjustment after delivery: Needs a teaching pendant.

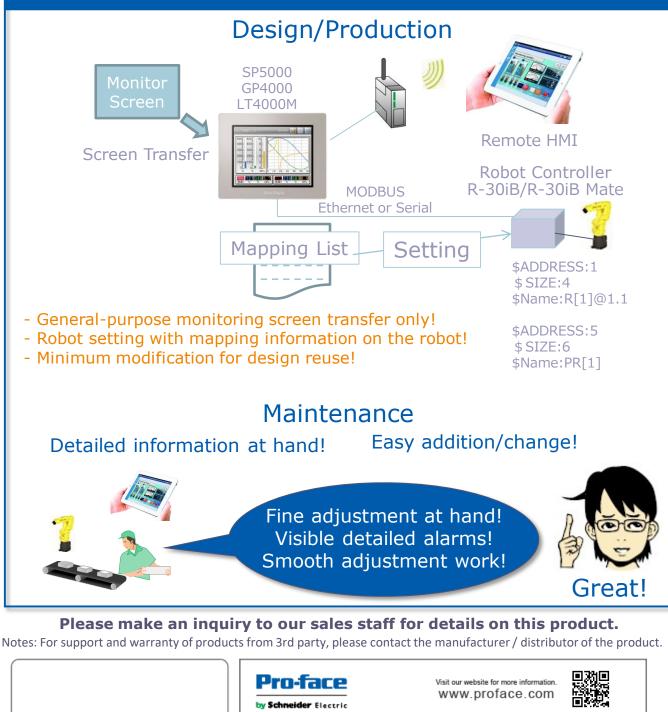


- Screens need to be re-designed even in design reuse and modification, which leads to high cost!

## Pro-face can solve the problem!

Solution (After) - General-purpose monitoring screen! - Robot setting list! No screen processing!

- Transfer of general-purpose screen. Operation screen is completed! - Easy robot setting according to the mapping list!



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