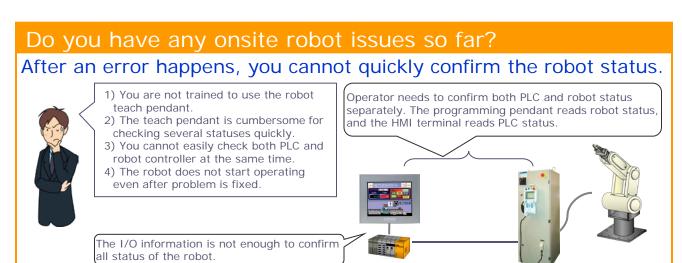


Yaskawa Robot HMI



Improve your equipment's capacity utilization and reduce your recovery time with a Touchscreen Operator Interface Terminal



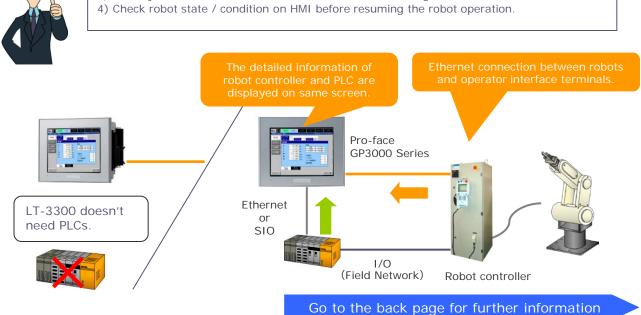


Pro-face provides the solution.

Quickly see the robot status with an Operator Interface Terminal



- 1) Check robot status without using a teach pendant (No need to get qualified person)
- 2) Follow a step-by-step recovery procedure displayed on a large HMI screen
- 3) Identify error causes faster and easier with HMI, accessing both PLC and Robot controller



Yaskawa Robot HMI



Monitor Robot and PLC status together on one HMI. With single-point access to all controllers, easier and faster to identify and fix.

Robot Status



Teach pendant is not required. Everybody can see what happened. Do not need to be trained on teach pendant for access.

Recovery Procedures



Recovery procedures can be displayed step-by-step on screen. Manuals are not required.*

* Requires a storage device

Operating Condition



You can check the robot operating conditions with a list. Mode, E-Stop, Starting Point, Preparing for Run.

Reduce the recovery time. Improve the capacity utilization of equipment.

Get details easily with direct connection between the robot and HMI. Pro-face HMI provides the following screens in a free application template project, which can be downloaded from the Pro-face website.

Job Program Monitor

When an error occurs in the robot, you can quickly identify at what step the operation stopped.



Robot Status Monitor

Displays position data and torque values. This data can be recorded as a log.*



* Requires the configuration for it and a Storage device.

Alarm History

Displays the last 100 alarm events that have occurred on the robot.



Robot Status Monitor List

Displays the status of up to 8 robots connected to one HMI.



Robot I / O Monitor

Displays general I/O and dedicated I/O along with comments. You can quickly check the I/O status.



Predictive Maintenance

Manages replacement time for grease and the battery on HMI.



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